

COMPLETELY CORRELATED MIXED FRACTIONAL BROWNIAN MOTION

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THE REFERENCE

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Long-range dependent completely correlated mixed fractional
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ABSTRACT

We introduce the long-range dependent completely correlated mixed fractional Brownian motion (ccmfBm). This is a process that is driven by a mixture of Brownian motion (Bm) and a long-range dependent completely correlated fractional Brownian motion (fBm, ccfBm) that is constructed from the Brownian motion via the Molchan–Golosov representation. Thus, there is a single Bm driving the mixed process. In the short time-scales the ccmfBm behaves like the Bm (it has Brownian Hölder index and quadratic variation). However, in the long time-scales it behaves like the fBm (it has long-range dependence governed by the fBm's Hurst index). We provide a transfer principle for the ccmfBm and use it to construct the Cameron–Martin–Girsanov–Hitsuda theorem and prediction formulas. Finally, we illustrate the ccmfBm by simulations.

OUTLINE

- 1 CONSTRUCTION OF CCMFBM
- 2 MOTIVATION
- 3 (INVERSE) TRANSFER PRINCIPLE
- 4 APPLICATIONS

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CONSTRUCTION OF CCMFBM

Take a Brownian motion (Bm) $W = (W_t)_{t \in [0, T]}$. Construct a completely correlated fractional Brownian motion (ccfBm, fBm) with $H > 1/2$ from the Bm by using the Molchan–Golosov kernel

$$B_t^H = \int_0^t K_H(t, s) dW_s,$$
$$K_H(t, s) = c(H) \frac{1}{s^{H-\frac{1}{2}}} \int_s^t \frac{u^{H-\frac{1}{2}}}{(u-s)^{\frac{3}{2}-H}} du,$$

and then, from the **SAME** Bm construct the long-range dependent completely correlated mixed fractional Brownian motion (ccmfBm):

$$X_t = X_t^{a,b,H} = aW_t + bB_t^H.$$

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MOTIVATION

The ccmfBm does not have stationary increments. A more natural mixed fractional Brownian motion (mfBm) would be

$$M_t = aW_t + bB_t^H,$$

where W and B^H are independent. This process has been studied in many articles.

However, ccmfBm is more convenient than mfBm because, as we will see, it has easier **INVERSE TRANSFER PRINCIPLE**. Also, the ccmfBm and the mfBm are similar in the sense that their short-time and long-time behaviors are mostly same (Hölder continuity, quadratic variation, long-range dependence).

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(INVERSE) TRANSFER PRINCIPLE

Let $L^2 = L^2([0, T])$. For a kernel $K: [0, T]^2 \rightarrow \mathbb{R}$ its ASSOCIATED OPERATOR is

$$Kf(t) = \int_0^T f(s)K(t, s) du.$$

The ADJOINT ASSOCIATED OPERATOR K^* of a kernel K is defined by linearly extending the relation

$$K^*\mathbf{1}_t(s) = K(t, s),$$

where $\mathbf{1}_t = \mathbf{1}_{[0,t]}$ is the indicator function.

(INVERSE) TRANSFER PRINCIPLE

If $K(\cdot, t)$ has bounded variation, then (more or less)

$$\mathbb{K}^* f(t) = f(t)K(T, t) + \int_t^T [f(u) - f(t)] K(du, t).$$

Since the Molchen–Golosoov kernel $K_H(t, s)$ for $H > 1/2$ is differentiable in t and $K_H(t, t-) = 0$, its adjoint associated operator can be written as

$$\mathbb{K}_H^* f(t) = \int_t^T f(u) \frac{\partial K_H}{\partial u}(u, t) du.$$

(INVERSE) TRANSFER PRINCIPLE

Let Λ be the closure of the indicator functions $\mathbf{1}_t$, $t \in [0, T]$, under the inner product generated by the relation

$$\langle \mathbf{1}_t, \mathbf{1}_s \rangle_\Lambda = R(t, s),$$

where R is the covariance of the ccmfBm.

Let \mathcal{H}_1 be the linear space, or first chaos, of X , i.e., the closure of the random variables X_t , $t \in [0, T]$, in $L^2(\Omega)$.

For $f \in \Lambda$ the abstract Wiener integral

$$\int_0^T f(t) dX_t$$

is the image of the isometry $\mathbf{1}_t \mapsto X_t$ from Λ to \mathcal{H}_1 .

Denote $L(t, s) = a\mathbf{1}_t(s) + bK_H(t, s)$ and let L and L^* be the associated and adjoint associated operators of L .

(INVERSE) TRANSFER PRINCIPLE

LEMMA (1)

L^* is a bounded operator on L^2 and it can be represented as

$$\begin{aligned} L^*f(t) &= af(t) + b \int_t^T f(u) \frac{\partial K_H}{\partial u}(u, t) du \\ &= af(t) + \frac{bc(H)}{t^{H-\frac{1}{2}}} \int_t^T f(u) \frac{u^{H-\frac{1}{2}}}{(u-t)^{\frac{3}{2}-H}} du. \end{aligned}$$

(INVERSE) TRANSFER PRINCIPLE

BEEF OF PROOF: K_H^* is bounded on L^2 , because

$$\begin{aligned}\|K_H^* f\|_2^2 &= \int_0^T \int_0^T f(t)f(s) \frac{\partial^2 R_H}{\partial s \partial t}(t, s) \, ds dt \\ &= H(2H - 1) \int_0^T \int_0^T \frac{f(t)f(s)}{|t - s|^{2-2H}} \, ds dt \\ &\leq H(2H - 1) \int_0^T \int_0^T \frac{f(t)^2}{|t - s|^{2-2H}} \, ds dt \\ &\leq H(2H - 1) \frac{T^{2H-1}}{H - \frac{1}{2}} \|f\|_2^2,\end{aligned}$$

where we have used the elementary estimate

$$2|f(t)f(s)| \leq f(t)^2 + f(s)^2$$

and symmetry.

(INVERSE) TRANSFER PRINCIPLE

LEMMA (2)

For each $t \in [0, T]$, the integral equation

$$\mathbf{1}_t(s) = aL^{-1}(t, s) + b \int_s^T L^{-1}(t, u) \frac{\partial K_H}{\partial u}(u, s) du$$

admits the unique L^2 -solution given by

$$L^{-1}(t, s) = \frac{1}{a} \mathbf{1}_t(s) + \frac{1}{a} \sum_{k=1}^{\infty} (-1)^k \left(\frac{b}{a}\right)^k \gamma_k(t, s)$$

where

$$\gamma_k(t, s) = \frac{c(H)^k \Gamma(H - \frac{1}{2})^k}{\Gamma(k(H - \frac{1}{2}))} \frac{1}{s^{H-\frac{1}{2}}} \int_s^t u^{H-\frac{1}{2}} (u-s)^{k(H-\frac{1}{2})-1} du.$$

(INVERSE) TRANSFER PRINCIPLE

BEEF OF PROOF: Denote

$$G(s, u) = -\frac{bc(H)}{a} \frac{u^{H-\frac{1}{2}}}{s^{H-\frac{1}{2}}(u-s)^{\frac{3}{2}-H}}.$$

Then Lemma 2 has the anti-Volterra equation of the second kind

$$\frac{1}{a} \mathbf{1}_t(s) = L^{-1}(t, s) - \int_s^t L^{-1}(t, u) G(s, u) du.$$

Lemma 1 implies that the solution of the equation in Lemma 2 is

$$L^{-1}(t, s) = \sum_{k=1}^{\infty} G^k \left[\frac{1}{a} \mathbf{1}_t \right] (s),$$

where G^0 is the identity operator and $G^{k+1} = GG^k$. Finally, we use induction with the formula ($\alpha = H - \frac{1}{2}$)

$$\int_s^u (v-s)^{k\alpha-1} (u-v)^{\alpha-1} dv = \frac{\Gamma(k\alpha)\Gamma(\alpha)}{\Gamma((k+1)\alpha)} (u-s)^{(k+1)\alpha-1}.$$

(INVERSE) TRANSFER PRINCIPLE

THEOREM (1)

The ccmfBm X is an invertible Gaussian Volterra process in the sense that the process W defined as the abstract Wiener integral

$$W_t = \int_0^t L^{-1}(t, s) dX_s$$

is the Bm from which the ccmfBm is constructed:

$$X_t = \int_0^t L(t, s) dW_s.$$

(INVERSE) TRANSFER PRINCIPLE

THEOREM ((INVERSE) TRANSFER PRINCIPLE)

Let $f \in L^2$. Let X be the ccmfBm constructed from the Bm W .
Then

$$\int_0^T f(t) dX_t = \int_0^T L^* f(t) dW_t,$$
$$\int_0^T f(t) dW_t = \int_0^T (L^*)^{-1} f(t) dX_t,$$

where

$$L^* f(t) = af(t) + b \int_t^T f(s) \frac{\partial K_H}{\partial s}(s, t) ds,$$
$$(L^*)^{-1} f(t) = f(t)L^{-1}(T, t) + \int_t^T [f(s) - f(t)] L^{-1}(ds, t).$$

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APPLICATIONS

- Cameron–Martin–Girsanov–Hitsuda theorem, equivalence of laws
- Maximum likelihood estimation
- Prediction laws, bridges, conditional laws
- Simulation
- Malliavin calculus
- ...

APPLICATIONS

PREDICTION

Denote

$$\Psi(t, s|u) = (\mathbf{L}^*)^{-1}[L(t, \cdot) - L(u, \cdot)](s)$$

Then

$$\begin{aligned}\hat{m}_t^X(u) &= \mathbf{E} \left[X_t | \mathcal{F}_u^X \right] \\ &= \mathbf{E} \left[\int_0^t L(t, s) dW_s | \mathcal{F}_u^W \right] \\ &= \int_0^u L(t, s) dW_s \\ &= \int_0^u L(u, s) dW_s + \int_0^u [L(t, s) - L(u, s)] dW_s \\ &= X_u - \int_0^u (\mathbf{L}^*)^{-1} [L(t, \cdot) - L(u, \cdot)](s) dX_s \\ &= X_u - \int_0^u \Psi(t, s|u) dX_s\end{aligned}$$

APPLICATIONS

PREDICTION

$$\begin{aligned}\hat{R}_X(t, s|u) &= \mathbf{E} \left[\left(X_t - \hat{m}_t^X(u) \right) \left(X_s - \hat{m}_s^X(u) \right) \middle| \mathcal{F}_u^X \right] \\ &= \mathbf{E} \left[\int_u^t L(t, x) dW_x \int_u^s L(s, x) dW_x \middle| \mathcal{F}_u^W \right] \\ &= \mathbf{E} \left[\int_u^t L(t, x) dW_x \int_u^s L(s, x) dW_x \right] \\ &= \int_u^{t \wedge s} L(t, x) L(s, x) dx \\ &= \int_0^{t \wedge s} L(t, x) L(s, x) dx - \int_0^u L(t, x) L(s, x) dx \\ &= R(t, s) - \int_0^u L(t, x) L(s, x) dx.\end{aligned}$$

Thank you for listening!
Any questions?