

WALK ON SPHERES ALGORITHMS FOR HELMHOLTZ AND LINEARIZED POISSON-BOLTZMANN EQUATIONS

Tommi Sottinen

University of Vaasa, Finland

Joint work with

Antti Rasila, Aalto University, Finland

Xuxin Yang, Hunan First Normal University, PRC

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ABSTRACT

We show that a constant-potential time-independent Schrödinger equation with Dirichlet boundary data can be reformulated as a Laplace equation with Dirichlet boundary data.

With this reformulation, which we call the Duffin correspondence, we provide a classical Walk On Spheres algorithm for Monte Carlo simulation of the solutions of the said boundary value problem.

OUTLINE

1 PRELIMINARIES

2 DUFFIN CORRESPONDENCE

3 WALK ON SPHERES (WOS) ALGORITHMS

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PRELIMINARIES

Let $x = (x_1, \dots, x_n)$. Denote

$$\Delta_x = \sum_{i=1}^n \frac{\partial^2}{\partial x_i^2}$$

We consider the Dirichlet-type boundary value problem of the Schrödinger equation with constant potential $\lambda \in \mathbb{R}$:

$$\begin{cases} \frac{1}{2}\Delta_x u(x) - \lambda u(x) = 0 & \text{on } x \in D, \\ u(y) = f(y) & \text{on } y \in \partial D. \end{cases}$$

Here D is a domain and f is (continuous and) bounded on ∂D . The case $\lambda > 0$ corresponds to the Yukawa equation, or the linearized Poisson–Boltzmann equation. The case $\lambda = 0$ is the Laplace equation. The case $\lambda < 0$ is the Helmholtz equation.

PRELIMINARIES

Conditions for the domain D of a Helmholtz–Yukawa problem to admit a unique bounded (strong) solution are best expressed by using probabilistic tools:

Let W be the n -dimensional Brownian motion, i.e., the unique Markov process with the generator $\frac{1}{2}\Delta_x$.

Let

$$\tau_D = \inf\{t > 0; W_t \notin D\}.$$

Let \mathbf{P}^x denote the probability measure under which $W_0 = x$.

ASSUMPTIONS

- 1 The domain D is *Wiener regular*, i.e.,

$$\mathbf{P}^y[\tau_D = 0] \quad \text{for all } y \in \partial D.$$

- 2 The domain D is *Wiener small*, i.e.,

$$\mathbf{P}^x[\tau_D < \infty] = 1 \quad \text{for all } x \in D.$$

- 3 Finally, we assume that the domain D is *gaugeable*, i.e.,

$$\sup_{x \in D} \mathbf{E}^x \left[e^{-\lambda \tau_D} \right] < \infty.$$

PRELIMINARIES

- 1 All domains with piecewise C^1 boundary are Wiener regular.
- 2 If any projection of the domain D on any subspace $\mathbb{R}^{n'}$, $n' \leq n$ is bounded, then D is Wiener small.
- 3 The gauge condition is satisfied if

$$\lambda > -\frac{1}{2} \text{Leb}(D)^{-2/n} \left(\frac{\pi^{n/2}}{\Gamma(n/2 + 1)} \right)^{2/n} j_{n/2-1,1}^2.$$

PROPOSITION (STOCHASTIC REPRESENTATION)

The Helmholtz–Yukawa equation admits the bounded solution

$$u(x) = \mathbf{E}^x \left[e^{-\lambda \tau_D} f(W_{\tau_D}) \right].$$

OUTLINE

1 PRELIMINARIES

2 DUFFIN CORRESPONDENCE

3 WALK ON SPHERES (WOS) ALGORITHMS

DUFFIN CORRESPONDENCE

Set $\bar{x} = (x, x') \in \mathbb{R}^n \times \mathbb{R}$ and

$$g(\lambda; x') = \begin{cases} \cos(\sqrt{2\lambda} x'), & \text{for } \lambda > 0, \\ \cosh(\sqrt{-2\lambda} x'), & \text{for } \lambda < 0. \end{cases},$$

$$I(\lambda) = \begin{cases} \left(-\frac{\pi}{2\sqrt{2\lambda}}, \frac{\pi}{2\sqrt{2\lambda}}\right), & \text{for } \lambda > 0, \\ \mathbb{R}, & \text{for } \lambda < 0, \end{cases}$$

$$\bar{D}(\lambda) = D \times I(\lambda),$$

$$\bar{u}(\lambda; \bar{x}) = u(x)g(\lambda; x'),$$

$$\bar{f}(\lambda; \bar{y}) = f(y)g(\lambda; y').$$

$$\begin{cases} \frac{1}{2} \Delta_{\bar{x}} \bar{u}(\lambda; \bar{x}) = 0 & \text{on } \bar{x} \in \bar{D}(\lambda), \\ \bar{u}(\lambda; \bar{y}) = \bar{f}(\lambda; \bar{y}) & \text{on } \bar{y} \in \partial \bar{D}(\lambda). \end{cases}$$

DUFFIN CORRESPONDENCE

THEOREM (DUFFIN CORRESPONDENCE)

u is the bounded solution to the Helmholtz–Yukawa equation iff \bar{u} is the bounded solution to the Laplace equation.

Let $\bar{W} = (W, W')$ be an $(n + 1)$ -dimensional Brownian motion and let $\tau_{I(\lambda)} = \inf\{t > 0; W'_t \notin I(\lambda)\}$.

COROLLARY (SIMPLE STOCHASTIC REPRESENTATION)

The Helmholtz–Yukawa equation admits the bounded solution

$$u(x) = \mathbf{E}^{x,0} [f(W_{\tau_D}) g(\lambda; W'_{\tau_D}) ; \tau_{I(\lambda)} > \tau_D].$$

OUTLINE

1 PRELIMINARIES

2 DUFFIN CORRESPONDENCE

3 WALK ON SPHERES (WOS) ALGORITHMS

WALK ON SPHERES (WOS) ALGORITHMS

DUFFIN WALK ON SPHERES (DWOS)

Denote

$$\begin{aligned}\tau_x &= \inf \{t > 0; W_t \notin D\}, \\ \tau'_{x'} &= \inf \{t > 0; W'_t \notin I(\lambda)\}, \\ \bar{\tau}_{\bar{x}} &= \inf \{t > 0; \bar{W} \notin \bar{D}(\lambda)\}.\end{aligned}$$

Note that τ_x and $\tau'_{x'}$ are independent, and $\bar{\tau}_{\bar{x}} = \min(\tau_x, \tau'_{x'})$.

For $x \in D$, denote $\bar{x} = (x, 0) \in \bar{D}(\lambda)$.

The stochastic approximation for $u(x)$ is

$$\hat{u}_K(x) = \frac{1}{K} \sum_{k=1}^K \bar{f} \left(\lambda; \bar{w}_{\bar{x}}^k(\bar{\tau}_{\bar{x}}^k) \right).$$

Here $\bar{\tau}_{\bar{x}}^k$ is the termination-step of the trajectory k . The trajectories are generated by the following DWOS Algorithm:

WALK ON SPHERES (WOS) ALGORITHMS

DUFFIN WALK ON SPHERES (DWOS)

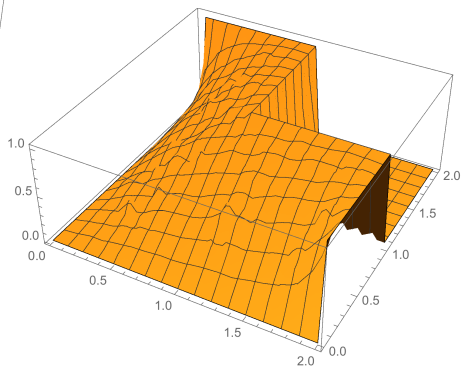
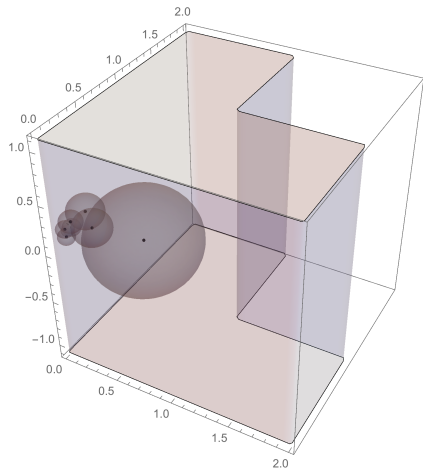
ALGORITHM (DWOS)

Fix a small parameter $\varepsilon > 0$.

- 1 Initialize: $\bar{w}_{\bar{x}}(0) = (w_x(0), (w')_0(0)) = (x, 0)$.
- 2 While $\text{dist}(\bar{w}_{\bar{x}}(j), \partial\bar{D}(\lambda)) > \varepsilon$:
 - 1 Set $r(j) = \text{dist}(\bar{w}_{\bar{x}}(j), \partial\bar{D}(\lambda))$.
 - 2 Sample $\xi(j)$ independently from the unit sphere $\partial B_{n+1}(0, 1)$.
 - 3 Set $\bar{w}_{\bar{x}}(j+1) = \bar{w}_{\bar{x}}(j) + r(j)\xi(j)$.
- 3 When $\text{dist}(\bar{w}_{\bar{x}}(j), \partial\bar{D}(\lambda)) \leq \varepsilon$:
- 4 Set pr $\bar{w}_{\bar{x}}(j)$ to be the orthogonal projection of $\bar{w}_{\bar{x}}(j)$ to $\partial\bar{D}(\lambda)$.
- 5 Return pr $\bar{w}_{\bar{x}}(j)$.

WALK ON SPHERES (WOS) ALGORITHMS

DUFFIN WALK ON SPHERES (DWOS)



WALK ON SPHERES (WOS) ALGORITHMS

WEIGHTED WALK ON SPHERES (WWOS)

Suppose we want use the WOS algorithm directly without the Duffin correspondence. To do this, we must estimate the term $e^{-\lambda\tau_D}$. Suppose the WOS algorithm takes T steps to hit the boundary with balls of radii r_1, r_2, \dots, r_T . The Weighted Walk On Spheres (WWOS) algorithm is based on the fact that the term $e^{-\lambda\tau_D}$ can be decomposed into independent terms

$$e^{-\lambda\tau_D} = e^{-\lambda\tau_{r_1}} e^{-\lambda\tau_{r_2}} \dots e^{-\lambda\tau_{r_T}},$$

where the τ_{r_j} 's are the exit times of the Brownian motion from balls of radius r_j , and these exit times are also independent of the exit locations from the ball. Consequently, at each step j of the WOS algorithm, the Brownian particle gains (or loses) an independent multiplicative weight that is given by

$$\mathbf{E}^{W_{\tau_{j-1}}} \left[e^{-\lambda\tau_{r_j}} \right] = \mathbf{E}^0 \left[e^{-\lambda\tau_{r_j}} \right].$$

WALK ON SPHERES (WOS) ALGORITHMS

WEIGHTED WALK ON SPHERES (WWOS)

By using the 1/2-self-similarity of the Brownian motion we see that

$$\mathbf{E}^0 \left[e^{-\lambda \tau_r} \right] = \mathbf{E}^0 \left[e^{-\lambda r^2 \tau_1} \right] = \psi(\lambda r^2).$$

For $\mu > 0$ the function ψ is well-known:

$$\psi(\mu) = \begin{cases} \frac{\mu^\nu}{2^\nu \Gamma(\nu+1) I_\nu(\mu)}, & n = 2\nu - 2 \geq 2, \\ \frac{1}{\cosh(\sqrt{2\lambda})}, & n = 1. \end{cases}$$

For $\mu < 0$, as far as we know, no simple formula for $\psi(\mu)$ is known. However, the distribution function of τ_1 is well-known:

$$\mathbf{P}^0 [\tau_1 \leq t] = 1 - \frac{1}{2^{\nu-1} \Gamma(\nu+1)} \sum_{i=1}^{\infty} \frac{j_{\nu,i}^{\nu-1}}{J_{\nu+1}(j_{\nu,i})} \exp \left\{ -\frac{1}{2} j_{\nu,i}^2 t \right\},$$

where $j_{\nu,i}$'s are the positive zeros J_ν in the increasing order.

WALK ON SPHERES (WOS) ALGORITHMS

WEIGHTED WALK ON SPHERES (WWOS)

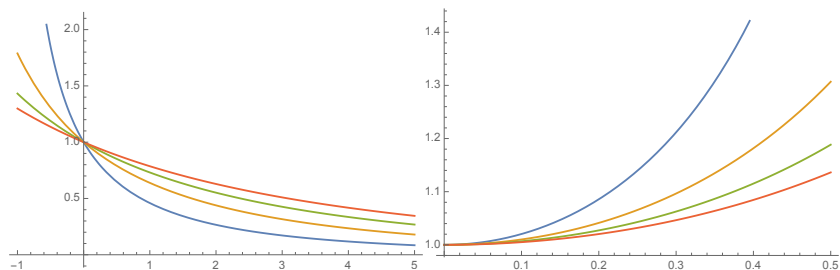


FIGURE : The function $\psi(\lambda)$ for $\lambda \in (-1, 5)$ for $n = 1, 2, 3, 4$, where $n = 1$ on the top (left). The function $\psi(-2r^2)$, $r > 0$, where the dimension are $n = 1, 2, 3, 4$, where $n = 1$ on the top (right).

WALK ON SPHERES (WOS) ALGORITHMS

WEIGHTED WALK ON SPHERES (WWOS)

The approximation for $u(x)$ is

$$\hat{u}_K(x) = \frac{1}{K} \sum_{k=1}^K c_x^k(\lambda) f(w_x^k(\tau_x^k)).$$

Here τ_x^k is the exit time for the each individual particle and $c_x^k(\lambda) = e^{-\lambda \tau_x^k}$.

The individual particle exit locations $w_x(\tau_x)$ and weights c_x^k are generated by the following WWOS algorithm:

WALK ON SPHERES (WOS) ALGORITHMS

WEIGHTED WALK ON SPHERES (WWOS)

ALGORITHM (WWOS)

Fix a small parameter $\varepsilon > 0$.

- 1 Initialize: $w_x(0) = x$, $c_x(0) = 0$
- 2 While $\text{dist}(w_x(j), D) > \varepsilon$:
 - 1 Set $r(j) = \text{dist}(w_x(j), \partial D)$.
 - 2 Sample $\xi(j)$ independently from the unit sphere $\partial B_n(0, 1)$.
 - 3 Set $w_x(j+1) = w_x(j) + r(j)\xi(j)$ and $c_x(j+1) = c_x(j)\psi(\lambda r(j)^2)$.
- 3 When $\text{dist}(w_x(j), \partial D) \leq \varepsilon$:
- 4 Set $\text{pr } w_x(j)$ to be the orthogonal projection of $w_x(j)$ to ∂D .
- 5 Return $\text{pr } w_x(j)$ and $c_x(j)$.

WALK ON SPHERES (WOS) ALGORITHMS

KILLING WALK ON SPHERES (KWOS)

For the Yukawa case $\lambda > 0$, the weight loss $e^{-\lambda\tau_D}$ of the particle can be interpreted as independent exponential killing of the particle.

Our estimator for $u(x)$ is

$$\hat{u}_K(x) = \frac{1}{K} \sum_{k \in K^*(\lambda)} f(w_x^k(\tau_x^k)),$$

where w_x^k , $k = 1, \dots, K$ are independent simulations of the trajectories Brownian particles starting from point x , and the set $K^*(\lambda) \subset \{1, \dots, K\}$ contains the particles that are not killed; τ_x^k is the termination-step time of the algorithm. The individual particles are generated by the following KWOS algorithm:

WALK ON SPHERES (WOS) ALGORITHMS

KILLING WALK ON SPHERES (KWOS)

ALGORITHM (KWOS)

Fix a small parameter $\varepsilon > 0$.

- 1 Initialize: $w_x(0) = x$.
- 2 While $\text{dist}(w_x(j), D) > \varepsilon$:
 - 1 Set $r(j) = \text{dist}(w_x(j), \partial D)$.
 - 2 Kill the particle with probability $1 - \psi(\lambda r(j)^2)$. If the particle is killed, the algorithm terminates and returns 0.
 - 3 Sample $\xi(j)$ independently from the unit sphere $\partial B_n(0, 1)$.
 - 4 Set $w_x(j+1) = w_x(j) + r(j)\xi(j)$.
- 3 When $\text{dist}(w_x(j), \partial D) \leq \varepsilon$:
- 4 Set $\text{pr } w_x(j)$ to be the orthogonal projection of $w_x(j)$ to ∂D .
- 5 Return $\text{pr } w_x(j)$.

Thank you for listening!
Any questions?