INTEGRATION-BY-PARTS CHARACTERIZATIONS OF GAUSSIAN PROCESSES

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 Integration-by-Parts Characterizations of Gaussian Processes *Collectanea Mathematica* 72, 25–41, doi:10.1007/s13348-019-00278-x The Stein's lemma characterizes the Gaussian distribution via an integration-by-parts formula.

We show that a similar integration-by-parts formula characterizes a wide class of Gaussian processes, the so-called Gaussian Fredholm processes.



- **1** Stein's (Multivariate) Lemma
- **2** Fredholm Representation
- **3** PATHWISE MALLIAVIN DIFFERENTIATION
- 4 Strong Form Integration-by-Parts Characterization
- **5** WEAK FORM INTEGRATION-BY-PARTS CHARACTERIZATION



1 Stein's (Multivariate) Lemma

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STEIN'S LEMMA, a.k.a. the INTEGRATION-BY-PARTS CHARACTERIZATION, states that a random variable X is standard normal if and only if

$$\mathsf{E}\left[f'(X)\right] = \mathsf{E}\left[Xf(X)\right]$$

for all smooth and bounded enough $f : \mathbb{R} \to \mathbb{R}$.

MULTIVARIATE STEIN'S LEMMA states that $X = (X_1, ..., X_d)$ is centered Gaussian with covariance R if and only if

$$\mathbf{E}\left[\sum_{i=1}^{d} X_{i} \frac{\partial}{\partial x_{i}} f(X)\right] = \mathbf{E}\left[\sum_{i=1}^{d} \sum_{j=1}^{d} R_{ij} \frac{\partial^{2}}{\partial x_{i} \partial x_{j}} f(X)\right]$$

for all smooth and bounded enough $f: \mathbb{R}^d \to \mathbb{R}$

Let $X = (X_t)_{t \in [0,1]}$ be a centered process with covariance R. The Multivariate Stein's Lemma suggests us to guess (WRONGLY!) that X is Gaussian if and only if

$$\mathbf{E}\left[\int_0^1 X_t D_t f(X) \,\mathrm{d}t\right] = \mathbf{E}\left[\int_0^1 \int_0^1 R(t,s) D_{t,s}^2 f(X) \,\mathrm{d}s \mathrm{d}t\right],$$

where *D* is some kind of MALLIAVIN DERIVATIVE.



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FREDHOLM REPRESENTATION THE THEOREM

THEOREM (FREDHOLM REPRESENTATION)

Let $X = (X_t)_{t \in [0,1]}$ be a separable centered Gaussian process. Then there exists a kernel $K \in L^2 \times L^2 = L^2([0,1]^2)$ and a Brownian motion $W = (W_t)_{t>0}$ such that

$$X_t = \int_0^1 K(t,s) \,\mathrm{d} W_s$$

if and only if the covariance R of X satisfies the trace condition

$$\int_0^T R(t,t)\,\mathrm{d}t < \infty.$$



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PATHWISE MALLIAVIN DIFFERENTIATION

Let $C_p^{\infty}(\mathbb{R}^n)$ denote the space of all polynomially bounded functions with polynomially bounded partial derivatives of all orders. Consider functionals $f: L^2 \to \mathbb{C}$ of the form

$$f(x)=g(z_1,\ldots,z_n),$$

where $n \in \mathbb{N}$ and $g \in \mathcal{C}^{\infty}_{p}(\mathbb{R}^{n})$, and

$$z_k = \int_0^1 e_k(t) \, \mathrm{d} x(t)$$

for some elementary functions $e_k \in \mathcal{E}$. For such f we write $f \in \mathcal{S}$. We call the elements of class \mathcal{S} the SMOOTH functionals. The PATHWISE MALLIAVIN DERIVATIVE of such $f \in \mathcal{S}$ is

$$D_t f(x) = \sum_{k=1}^n \frac{\partial}{\partial z_k} g(z_1, \ldots, z_n) e_k(t).$$

More generally, by iteration for every $m \in \mathbb{N}$, the pathwise Malliavin derivative of order m is defined as follows: for every $t_1, ..., t_m \in [0, 1]$,

$$D_{t_m,...,t_1}^m f(x) = \sum_{1 \le k_1,...,k_m \le n} \frac{\partial^m}{\partial z_{k_1} \cdots \partial z_{k_m}} g(z_{k_1},...,z_{k_n}) (e_{k_1} \otimes \cdots \otimes e_{k_m}) (t_1,...,t_m).$$

Remark

Let $f \in S$ and $y \in L^2$. Then

$$\langle \nabla f(x), Iy \rangle_{L^2} = \langle Df(x), y \rangle_{L^2}$$



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STRONG FORM INTEGRATION-BY-PARTS CHARACTERIZATION

Let K^* extend linearly the relation $K^* \mathbf{1}_t(s) = K(t, s)$, where $\mathbf{1}_t = \mathbf{1}_{[0,t)}$.

Theorem

Let $K \in L^2 \times L^2$. The co-ordinate process $X : \Omega \to L^2$ is centered Gaussian with Fredholm kernel K if and only if

$$\mathbf{E}[X_t D_t f(X)] = \mathbf{E}\left[\int_0^1 K(t,s) K^* \left[D_{t,\cdot}^2 f(X)\right](s) \, \mathrm{d}s\right]$$

for all $t \in [0, 1]$ and $f \in S$.

Suppose the co-ordinate process $X: \Omega \to L^2$ satisfies the Strong IBP Formula. We begin by considering the covariance function of X, which will justify the use of the Fubini theorem later and make a tedious variance calculations unnecessary. For this, take $f(X) = \frac{1}{2}X_u^2$ for some $u \in [0, 1]$. Then $f \in S$. We have $D_t f(X) = X_u \mathbf{1}_u(t)$ and $D_{t,s}^2 f(X) = \mathbf{1}_u(s)\mathbf{1}_u(t)$. Consequently,

$$\mathbf{E}[X_t X_u] \mathbf{1}_u(t) = \mathbf{E}\left[\int_0^1 \mathcal{K}(t,s) \mathcal{K}^* [\mathbf{1}_u](s) \, \mathrm{d}s\right] \mathbf{1}_u(t)$$

= $\int_0^1 \mathcal{K}(t,s) \mathcal{K}(u,s) \, \mathrm{d}s \, \mathbf{1}_u(t)$
= $\mathcal{R}(t,u) \mathbf{1}_u(t).$

This shows that X has the covariance function R given by the Fredholm kernel K.

In particular, we have

$$\mathsf{E}\left[X_t^2\right] = \int_0^1 \mathcal{K}(t,s)^2 \,\mathrm{d}s,$$

and since $K \in L^2 \times L^2$, we have $\int_0^1 \mathbf{E} [X_t^2] dt < \infty$ which justifies the use of the Fubini theorem in the rest of the proof. Next we are going to show that any finite linear combination

$$Z = \sum_{k=1}^{n} a_k \left(X_{t_k} - X_{t_{k-1}} \right) = \int_0^1 e(t) \, \mathrm{d}X_t$$

with $e = \sum_{k}^{n} a_{k} \mathbf{1}_{(t_{k-1}, t_{k}]} \in \mathcal{E}$ is a Gaussian random variable. Now, note that for every θ the complex-valued exponential functional $e^{i\theta Z} = \cos(\theta Z) + i\sin(\theta Z)$ belongs to S, meaning that the real and imaginary parts both belong to S.

Let φ be the characteristic function of Z. Then

$$\begin{array}{lll} D_t \mathrm{e}^{\mathrm{i}\theta Z} &=& \mathrm{i}\theta e(t) \, \mathrm{e}^{\mathrm{i}\theta Z}, \\ D_{t,s}^2 \mathrm{e}^{\mathrm{i}\theta Z} &=& -\theta^2 e(t) e(s) \, \mathrm{e}^{\mathrm{i}\theta Z}, \end{array}$$

Hence $\mathbf{E} \left[X_t D_t e^{i\theta Z} \right] = i\theta e(t) \mathbf{E} \left[X_t e^{i\theta Z} \right]$. Also, by a direct application of Fubini theorem

$$\mathbf{E} \left[\int_{0}^{1} \mathcal{K}(t,s) \mathcal{K}^{*} \left[D_{t,\cdot}^{2} e^{\mathrm{i}\theta Z} \right](s) \,\mathrm{d}s \right]$$

$$= -\mathbf{E} \left[\int_{0}^{1} \mathcal{K}(t,s) \mathcal{K}^{*} \left[\theta^{2} e(t) e(\cdot) e^{\mathrm{i}\theta Z} \right](s) \,\mathrm{d}s \right]$$

$$= -\theta^{2} e(t) \mathbf{E} \left[\int_{0}^{1} \mathcal{K}(t,s) \mathcal{K}^{*} \left[e(\cdot) e^{\mathrm{i}\theta Z} \right](s) \,\mathrm{d}s \right]$$

$$= -\theta^{2} e(t) \int_{0}^{1} \mathcal{K}(t,s) e^{*}(s) \,\mathrm{d}s \, \mathbf{E} \left[e^{\mathrm{i}\theta Z} \right],$$

where we have denoted $e^* = K^* e$. Consequently, the Strong IBP Formula yields

$$\mathrm{i} \mathbf{E} \left[X_t \mathrm{e}^{i\theta Z} \right] = - heta \int_0^1 \mathcal{K}(t,s) e^*(s) \,\mathrm{d} s \,\, \varphi(heta).$$

By Fubini theorem justified by the covariance computation, we also have

$$arphi'(heta) = \mathsf{E}\left[\mathrm{i} Z \, \mathrm{e}^{\mathrm{i} heta Z}
ight].$$

Thus we obtain that $\varphi'(heta) = -c heta\, \varphi(heta)$, where we have denoted

$$c = \int_0^1 \left(\sum_{k=1}^n a_k \left(\mathcal{K}(t_k, s) - \mathcal{K}(t_{k-1}, s) \right) e^*(s)
ight) \, \mathrm{d}s < \infty.$$

This implies that $\varphi(\theta) = e^{-\frac{1}{2}c\theta^2}$, and since φ is a characteristic function, c > 0. Consequently, Z is a centered Gaussian random variable with variance c.

Since the co-ordinate process $X: \Omega \to L^2$ is Gaussian, we have the full power of Malliavin calculus at our disposal.

In particular, we can use Malliavin IBP Formula

$$\mathbf{E}[FG] = \mathbf{E}[F]\mathbf{E}[G] + \mathbf{E}\left[\langle DF, -DL^{-1}G \rangle_{\mathcal{H}}\right].$$

with $F = D_t f(X)$ and $G = X_t$. Since $\mathbf{E}[X_t] = 0$, we obtain
 $\mathbf{E}[X_t D_t f(X)] = \mathbf{E}\left[\langle D_{t,\cdot}^2 f(X), -DL^{-1}X_t \rangle_{\mathcal{I}}\right]$

But $-DL^{-1}X_t = \mathbf{1}_t$ and K^* is an isometry between \mathcal{I} and L^2 . Therefore, by noticing that $K^*\mathbf{1}_t(s) = K(t, s)$, we obtain

$$\begin{aligned} \mathbf{E}\left[X_{t}D_{t}f(X)\right] &= \mathbf{E}\left[\left\langle D_{t,\cdot}^{2}f(X),\mathbf{1}_{t}\right\rangle_{\mathcal{I}}\right] \\ &= \mathbf{E}\left[\left\langle \mathcal{K}^{*}D_{t,\cdot}^{2}f(X),\mathcal{K}^{*}\mathbf{1}_{t}\right\rangle_{L^{2}}\right] \\ &= \mathbf{E}\left[\int_{0}^{1}\mathcal{K}^{*}\left[D_{t,\cdot}^{2}f(X)\right](s)\mathcal{K}^{*}\mathbf{1}_{t}(s)\,\mathrm{d}s\right] \\ &= \mathbf{E}\left[\int_{0}^{1}\mathcal{K}^{*}\left[D_{t,\cdot}^{2}f(X)\right](s)\mathcal{K}(t,s)\,\mathrm{d}s\right] \end{aligned}$$

showing the claim.



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WEAK FORM INTEGRATION-BY-PARTS CHARACTERIZATION

By using Fubini to the Strong IBP Formula, we obtain

THEOREM (WEAK INTEGRATION-BY-PARTS CHARACTERIZATION)

Let $K \in L^2 \times L^2$. Assume that the co-ordinate process $X : \Omega \to L^2$ satisfies $X \in L^2(dt \otimes \mathbf{P})$, i.e.

$$\int_0^1 \mathbf{E}\left[X_t^2\right] \mathrm{d}t < \infty.$$

Then X is centered Gaussian with the Fredholm kernel K if and only if

$$\mathbf{E}\left[\int_{0}^{1} X_{t} D_{t} f(X) \, \mathrm{d}t\right] = \mathbf{E}\left[\int_{0}^{1} \int_{0}^{1} K(t,s) K^{*}\left[D_{t,\cdot}^{2} f(X)\right](s) \, \mathrm{d}s \mathrm{d}t\right]$$

for all $f \in S$.

Thank you for listening! Any questions?